

INTEGRATED MICROGRID DEVELOPMENT

USING REAL-TIME CONTROLLER HARDWARE-IN-THE-LOOP CAPABILITY*

*observe the system behavior under multiple network configurations, with load shedding, islanding and reconnection on high time scale range.

MOTIVATION

- Rapid increase of power electronics (PE) penetration shifts the grid dominant physics with substantial kinetic inertia and inductive impedance to digitally manipulated power
- System modeling complexity increases, and dynamic time constants accelerate by three or more orders of magnitude
- A high fidelity, cost-effective tool to test and predict system performance under diverse operating conditions are of utmost importance for microgrid developers.

REAL WORLD PROBLEM EXAMPLE

- Hawaii plans to have 100% renewable generation by 2045, transforming its grids into early pilots of Digital Power Systems
- Microsecond phenomena of fast digital controllers and environmental effects complicate the evaluation of system control, stability, and protection



SOLUTION

- High fidelity, real time simulator with controller hardware-in-the-loop functionality
- Microgrid implementation with high fidelity models of distributed energy resources, protective devices, complex loads, transmission lines and transformers
- Multi-rate simulation from 0.5 microsecond time step.



Example: Lincoln Lab Banshee microgrid.

1. DERs and protective devices:

- a. Diesel generator Synchronous machine with speed and voltage control loops.
- **b.** Natural Gas genset Synchronous machine with speed and voltage control loops implemented with combined heat and power approach.
- **c.** Solar inverter High fidelity switching model of a three-phase inverter. Connected to a detailed model of a photovoltaic panel.
- **d.** Energy storage inverter High fidelity switching model of a three-phase inverter. Connected to a detailed model of a battery bench.
- e. Protection relays A device for sensing grid currents and voltages and controlling a circuit breaker. Can be fully simulated or integrated via Hardware-in-the-loop.
- 2. Controller Hardware-in-the-loop microgrid testbed
 - a. Four Typhoon HIL high fidelity real time simulators connected in parallel. -
 - b. Two Woodward Easygen controllers for diesel and natural gas gensets.





- c. Two EPC controllers for energy storage and solar inverters.
- d. Three Schweitzer relay for point of common coupling circuit breakers.
- e. Eaton microgrid controller Communicates with simulated devices and real controllers though standard protocols such as Modbus and IEC61850. Operates with a time scale in the range of minutes, hours and days.
- 3. Real time measurement and data logging.

CONCLUSION

The controller hardware-in-the-loop (C-HIL) approach combines high fidelity models for different components with wide range of time scales. C-HIL provides a costeffective, reliable testbed through which to examine any range of configurations and operating conditions event before investing in hardware.

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